

# EP16: Missing Values in Clinical Research: Multiple Imputation

## 2. Imputation Step

Nicole Erler

Department of Biostatistics, Erasmus Medical Center

✉ [n.erler@erasmusmc.nl](mailto:n.erler@erasmusmc.nl)

# Univariate Missing Data

---

How can we actually get imputed values?

# Univariate Missing Data

---

## How can we actually get imputed values?

For now: assume only one continuous variable has missing values (**univariate missing data**).

$X_1$	$X_2$	$X_3$	$X_4$
✓	NA	✓	✓
✓	✓	✓	✓
✓	NA	✓	✓
⋮	⋮	⋮	⋮

# Univariate Missing Data

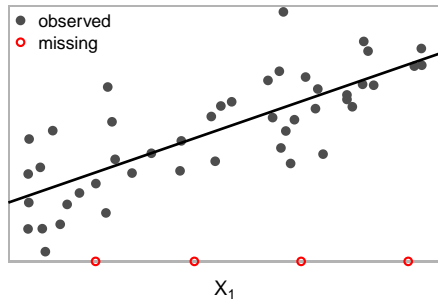
How can we actually get imputed values?

For now: assume only one continuous variable has missing values (**univariate missing data**).

$X_1$	$X_2$	$X_3$	$X_4$
✓	NA	✓	✓
✓	✓	✓	✓
✓	NA	✓	✓
⋮	⋮	⋮	⋮

**Idea:** Predict values

Model:  $x_{i2} = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i3} + \beta_3 x_{i4} + \varepsilon_i$



# Univariate Missing Data

---

## How can we actually get imputed values?

For now: assume only one continuous variable has missing values (**univariate missing data**).

$X_1$	$X_2$	$X_3$	$X_4$
✓	NA	✓	✓
✓	✓	✓	✓
✓	NA	✓	✓
⋮	⋮	⋮	⋮

**Idea:** Predict values

$$\text{Model: } x_{i2} = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i3} + \beta_3 x_{i4} + \varepsilon_i$$

Imputed/predicted value:

$$\hat{x}_{i2} = \hat{\beta}_0 + \hat{\beta}_1 x_{i1} + \hat{\beta}_2 x_{i3} + \hat{\beta}_3 x_{i4}$$

# Univariate Missing Data

---

## Problem:

- ▶ We can obtain **only one imputed value** per missing value (but we wanted a whole distribution).
- ▶ The predicted values do not take into account the added **uncertainty** due to the missing values.

# Univariate Missing Data

---

## Problem:

- ▶ We can obtain **only one imputed value** per missing value (but we wanted a whole distribution).
  - ▶ The predicted values do not take into account the added **uncertainty** due to the missing values.
- ➔ We need to take into account **two sources of uncertainty**:
- ▶ The **parameters** are estimated with **uncertainty** (represented by the standard error).
  - ▶ There is **random variation / prediction error** (variation of the residuals).

# Univariate Missing Data

---

## **Taking into account uncertainty about the parameters:**

We assume that  $\beta$  **has a distribution**, and we can sample realizations of  $\beta$  from that distribution.

When plugging the different realizations of  $\beta$  into the predictive model, we obtain **slightly different regression lines**.



# Univariate Missing Data

---

## Taking into account uncertainty about the parameters:

We assume that  $\beta$  **has a distribution**, and we can sample realizations of  $\beta$  from that distribution.

When plugging the different realizations of  $\beta$  into the predictive model, we obtain **slightly different regression lines**.

With each set of coefficients, we also get slightly **different predicted values**.

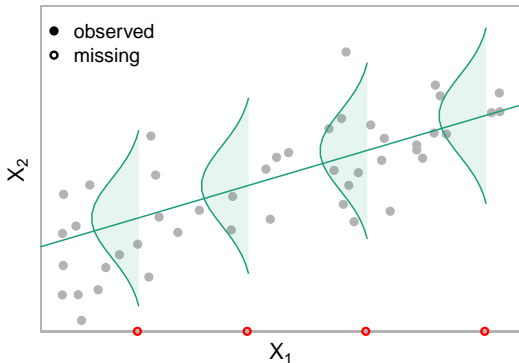
# Univariate Missing Data

## Taking into account the prediction error:

The model does not fit the data perfectly: observations are scattered around the regression lines.

We assume that the **data have a distribution**, where

- ▶ the **mean** for each value is given by the **predictive model**, and
- ▶ the **variance** is determined by the variance of the residuals  $\epsilon$ .



# Univariate Missing Data

---

## Taking into account the prediction error:

The model does not fit the data perfectly: observations are scattered around the regression lines.

We assume that the **data have a distribution**, where

- ▶ the **mean** for each value is given by the **predictive model**, and
  - ▶ the **variance** is determined by the variance of the residuals  $\epsilon$ .
- ➔ sample imputed values from this distribution.

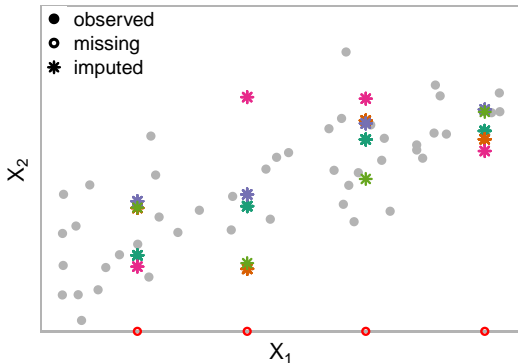
# Univariate Missing Data

## Taking into account the prediction error:

The model does not fit the data perfectly: observations are scattered around the regression lines.

We assume that the **data have a distribution**, where

- ▶ the **mean** for each value is given by the **predictive model**, and
  - ▶ the **variance** is determined by the variance of the residuals  $\epsilon$ .
- ➔ sample imputed values from this distribution.



In the end, we obtain one imputed dataset for each colour.

# Multivariate Missing Data

---

## Multivariate missing data:

What if we have **missing values in more than one variable?**

# Multivariate Missing Data

---

## Multivariate missing data:

What if we have **missing values in more than one variable**?

In case of **monotone missing values** we can use the technique for univariate missing data in a chain:

impute  $x_4$  given  $x_1$

impute  $x_3$  given  $x_1$  and  $x_4$

impute  $x_2$  given  $x_1, x_4$  and  $x_3$

$X_1$	$X_2$	$X_3$	$X_4$
✓	NA	✓	✓
✓	NA	NA	✓
✓	NA	NA	NA
⋮	⋮	⋮	⋮

# Multivariate Missing Data

## Multivariate missing data:

What if we have **missing values in more than one variable**?

In case of **monotone missing values** we can use the technique for univariate missing data in a chain:

impute  $x_4$  given  $x_1$

impute  $x_3$  given  $x_1$  and  $x_4$

impute  $x_2$  given  $x_1, x_4$  and  $x_3$

When we have **non-monotone missing data** there is no sequence without conditioning on unobserved values.

$X_1$	$X_2$	$X_3$	$X_4$
✓	NA	✓	✓
✓	NA	NA	✓
✓	NA	NA	NA
⋮	⋮	⋮	⋮

$X_1$	$X_2$	$X_3$	$X_4$
✓	NA	✓	✓
✓	✓	NA	NA
✓	NA	✓	NA
⋮	⋮	⋮	⋮

# Multivariate Missing Data

---

There are **two popular approaches** for the imputation step in **multivariate non-monotone** missing data:

## Fully Conditional Specification

- ▶ Multiple Imputation using Chained Equations (**MICE**)
- ▶ sometimes also: sequential regression
- ▶ implemented in SPSS, R, Stata, SAS, ...
- ▶ our focus here



# Multivariate Missing Data

---

There are **two popular approaches** for the imputation step in **multivariate non-monotone** missing data:

## Fully Conditional Specification

- ▶ Multiple Imputation using Chained Equations (**MICE**)
- ▶ sometimes also: sequential regression
- ▶ implemented in SPSS, R, Stata, SAS, ...
- ▶ our focus here

## Joint Model Imputation

(more details later)

## MICE / FCS

---

**MICE** (**M**ultiple **I**mputation using **C**hained **E**quations) or  
**FCS** (multiple imputation using **F**ully **C**onditional **S**pecification)

extends univariable imputation to the setting with multivariate non-monotone missingness:

MICE / FCS

- ▶ imputes **multivariate** missing data on a **variable-by-variable** basis,
- ▶ using the technique for univariate missing data.

## MICE / FCS

---

**MICE** (**M**ultiple **I**mputation using **C**hained **E**quations) or **FCS** (multiple imputation using **F**ully **C**onditional **S**pecification)

extends univariable imputation to the setting with multivariate non-monotone missingness:

MICE / FCS

- ▶ imputes **multivariate** missing data on a **variable-by-variable** basis,
- ▶ using the technique for univariate missing data.

Moreover, MICE/FCS is

- ▶ an **iterative** procedure, specifically
- ▶ a **Markov Chain Monte Carlo (MCMC)** method,
- ▶ uses the idea of the **Gibbs sampler**

## Markov Chain Monte Carlo

- ▶ a technique to **draw samples from a complex probability distribution**
- ▶ works via creating a chain of random variables (a Markov chain)
  - ➔ The distribution that each element in the chain is sampled from depends on the value of the previous element.
- ▶ When certain conditions are met, the chain eventually stabilizes
- ▶ samples of the chain are then a sample from the complex distribution of interest

## Gibbs sampling

- ▶ a MCMC method to obtain a **sample from a multivariate distribution**
- ▶ the multivariate distribution is split into a set of univariate full conditional distributions
- ▶ a sample from the multivariate distribution can be obtained by repeatedly drawing from each of the univariate distributions

## MICE / FCS: Notation

- ▶  $X$ :  $n \times p$  data matrix with  $n$  rows and  $p$  variables  $x_1, \dots, x_p$
- ▶  $R$ :  $n \times p$  missing indicator matrix containing 0 (missing) or 1 (observed)

$$\mathbf{X} = \begin{array}{c} X_{-2} \quad X_2 \quad X_{-2} \\ \begin{array}{cccc} x_{1,1} & x_{1,2} & \dots & x_{1,p} \\ x_{2,1} & x_{2,2} & \dots & x_{2,p} \\ \vdots & \vdots & \ddots & \vdots \\ x_{n,1} & x_{n,2} & \dots & x_{n,p} \end{array} \end{array}$$

$$\mathbf{R} = \begin{array}{cccc} R_{1,1} & R_{1,2} & \dots & R_{1,p} \\ R_{2,1} & R_{2,2} & \dots & R_{2,p} \\ \vdots & \vdots & \ddots & \vdots \\ R_{n,1} & R_{n,2} & \dots & R_{n,p} \end{array}$$

## MICE / FCS: Notation

- ▶  $X$ :  $n \times p$  data matrix with  $n$  rows and  $p$  variables  $x_1, \dots, x_p$
- ▶  $R$ :  $n \times p$  missing indicator matrix containing 0 (missing) or 1 (observed)

$$\mathbf{X} = \begin{array}{c} X_{-2} \quad X_2 \quad X_{-2} \\ \begin{array}{cccc} X_{1,1} & X_{1,2} & \dots & X_{1,p} \\ X_{2,1} & X_{2,2} & \dots & X_{2,p} \\ \vdots & \vdots & \ddots & \vdots \\ X_{n,1} & X_{n,2} & \dots & X_{n,p} \end{array} \end{array}$$

$$\mathbf{R} = \begin{array}{cccc} R_{1,1} & R_{1,2} & \dots & R_{1,p} \\ R_{2,1} & R_{2,2} & \dots & R_{2,p} \\ \vdots & \vdots & \ddots & \vdots \\ R_{n,1} & R_{n,2} & \dots & R_{n,p} \end{array}$$

**For example:**

$$\mathbf{X} = \begin{array}{cccc} X_1 & X_2 & X_3 & X_4 \\ \hline \checkmark & \text{NA} & \checkmark & \checkmark \\ \checkmark & \checkmark & \text{NA} & \text{NA} \\ \checkmark & \text{NA} & \checkmark & \text{NA} \end{array}$$

$$\rightarrow \mathbf{R} = \begin{array}{cccc} 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \end{array}$$

# The MICE Algorithm (Van Buuren, 2012)

---

- 1: **for**  $j$  in  $1, \dots, p$ : ▷ Setup
- 2:     Specify imputation model for variable  $X_j$   
        $p(X_j^{mis} \mid X_j^{obs}, X_{-j}, R)$
- 3:     Fill in starting imputations  $\dot{X}_j^0$  by random draws from  $X_j^{obs}$ .
- 4: **end for**



# The MICE Algorithm (Van Buuren, 2012)

---

- 1: **for**  $j$  in  $1, \dots, p$ : ▷ Setup
- 2:     Specify imputation model for variable  $X_j$   
       $p(X_j^{mis} \mid X_j^{obs}, X_{-j}, R)$
- 3:     Fill in starting imputations  $X_j^0$  by random draws from  $X_j^{obs}$ .
- 4: **end for**
  
- 5: **for**  $t$  in  $1, \dots, T$ : ▷ loop through iterations
- 6:     **for**  $j$  in  $1, \dots, p$ : ▷ loop through variables
  
  
  
  
  
  
  
  
  
  
- 10:     **end for**
- 11: **end for**

# The MICE Algorithm (Van Buuren, 2012)

- 1: **for**  $j$  in  $1, \dots, p$ : ▷ Setup
- 2:     Specify imputation model for variable  $X_j$   
       $p(X_j^{mis} \mid X_j^{obs}, X_{-j}, R)$
- 3:     Fill in starting imputations  $\dot{X}_j^0$  by random draws from  $X_j^{obs}$ .
- 4: **end for**
  
- 5: **for**  $t$  in  $1, \dots, T$ : ▷ loop through iterations
- 6:     **for**  $j$  in  $1, \dots, p$ : ▷ loop through variables
- 7:        Define currently complete data except  $X_j$   
           $\dot{X}_{-j}^t = (\dot{X}_1^t, \dots, \dot{X}_{j-1}^t, \dot{X}_{j+1}^{t-1}, \dots, \dot{X}_p^{t-1})$ .
  
- 10:     **end for**
- 11: **end for**

# The MICE Algorithm (Van Buuren, 2012)

- 1: **for**  $j$  in  $1, \dots, p$ : ▷ Setup
- 2:     Specify imputation model for variable  $X_j$   
       $p(X_j^{mis} \mid X_j^{obs}, X_{-j}, R)$
- 3:     Fill in starting imputations  $\dot{X}_j^0$  by random draws from  $X_j^{obs}$ .
- 4: **end for**
  
- 5: **for**  $t$  in  $1, \dots, T$ : ▷ loop through iterations
- 6:     **for**  $j$  in  $1, \dots, p$ : ▷ loop through variables
- 7:         Define currently complete data except  $X_j$   
           $\dot{X}_{-j}^t = (\dot{X}_1^t, \dots, \dot{X}_{j-1}^t, \dot{X}_{j+1}^{t-1}, \dots, \dot{X}_p^{t-1})$ .
- 8:         Draw parameters  $\hat{\theta}_j^t \sim p(\theta_j^t \mid X_j^{obs}, \dot{X}_{-j}^t, R)$ .
  
- 10:     **end for**
- 11: **end for**

# The MICE Algorithm (Van Buuren, 2012)

- 1: **for**  $j$  in  $1, \dots, p$ : ▷ Setup
- 2:     Specify imputation model for variable  $X_j$   
        $p(X_j^{mis} \mid X_j^{obs}, X_{-j}, R)$
- 3:     Fill in starting imputations  $\dot{X}_j^0$  by random draws from  $X_j^{obs}$ .
- 4: **end for**
  
- 5: **for**  $t$  in  $1, \dots, T$ : ▷ loop through iterations
- 6:     **for**  $j$  in  $1, \dots, p$ : ▷ loop through variables
- 7:         Define currently complete data except  $X_j$   
            $\dot{X}_{-j}^t = (\dot{X}_1^t, \dots, \dot{X}_{j-1}^t, \dot{X}_{j+1}^{t-1}, \dots, \dot{X}_p^{t-1})$ .
- 8:         Draw parameters  $\hat{\theta}_j^t \sim p(\theta_j^t \mid X_j^{obs}, \dot{X}_{-j}^t, R)$ .
- 9:         Draw imputations  $\dot{X}_j^t \sim p(X_j^{mis} \mid \dot{X}_{-j}^t, R, \hat{\theta}_j^t)$ .
- 10:     **end for**
- 11: **end for**

# The MICE Algorithm (Van Buuren, 2012)

- 1: **for**  $j$  in  $1, \dots, 4$ : ▷ Setup
- 2:     Specify imputation model for variable  $X_j$   
       $p(X_j^{mis} \mid X_j^{obs}, X_{-j}, R)$
- 3:     Fill in starting imputations  $\dot{X}_j^0$  by random draws from  $X_j^{obs}$ .
- 4: **end for**
  
- 5: **for**  $t = 1$ : ▷ loop through iterations
- 6:     **for**  $j = 1$ : ▷ loop through variables
- 7:         Define currently complete data except  $X_1$   
           $\dot{X}_{-1}^1 = (\dot{X}_2^0, \dot{X}_3^0, \dot{X}_4^0)$ .
- 8:         Draw parameters  $\theta_1^1 \sim p(\theta_1^1 \mid X_1^{obs}, \dot{X}_{-1}^1, R)$ .
- 9:         Draw imputations  $\dot{X}_1^1 \sim p(X_1^{mis} \mid \dot{X}_{-1}^1, R, \theta_1^1)$ .
- 10:     **end for**
- 11: **end for**

# The MICE Algorithm (Van Buuren, 2012)

- 1: **for**  $j$  in  $1, \dots, 4$ : ▷ Setup
- 2:     Specify imputation model for variable  $X_j$   
       $p(X_j^{mis} \mid X_j^{obs}, X_{-j}, R)$
- 3:     Fill in starting imputations  $\dot{X}_j^0$  by random draws from  $X_j^{obs}$ .
- 4: **end for**
  
- 5: **for**  $t = 1$ : ▷ loop through iterations
- 6:     **for**  $j = 2$ : ▷ loop through variables
- 7:        Define currently complete data except  $X_2$   
           $\dot{X}_{-2}^1 = (\dot{X}_1^1, \dot{X}_3^0, \dot{X}_4^0)$ .
- 8:        Draw parameters  $\dot{\theta}_2^1 \sim p(\theta_2^1 \mid X_2^{obs}, \dot{X}_{-2}^1, R)$ .
- 9:        Draw imputations  $\dot{X}_2^1 \sim p(X_2^{mis} \mid \dot{X}_{-2}^1, R, \dot{\theta}_2^1)$ .
- 10:     **end for**
- 11: **end for**

# The MICE Algorithm (Van Buuren, 2012)

- 1: **for**  $j$  in  $1, \dots, 4$ : ▷ Setup
- 2:     Specify imputation model for variable  $X_j$   
       $p(X_j^{mis} | X_j^{obs}, X_{-j}, R)$
- 3:     Fill in starting imputations  $\dot{X}_j^0$  by random draws from  $X_j^{obs}$ .
- 4: **end for**
  
- 5: **for**  $t = 1$ : ▷ loop through iterations
- 6:     **for**  $j = 3$ : ▷ loop through variables
- 7:         Define currently complete data except  $X_3$   
           $\dot{X}_{-3}^1 = (\dot{X}_1^1, \dot{X}_2^1, \dot{X}_4^0)$ .
- 8:         Draw parameters  $\dot{\theta}_3^1 \sim p(\theta_3^1 | X_3^{obs}, \dot{X}_{-3}^1, R)$ .
- 9:         Draw imputations  $\dot{X}_3^1 \sim p(X_3^{mis} | \dot{X}_{-3}^1, R, \dot{\theta}_3^1)$ .
- 10:     **end for**
- 11: **end for**

# The MICE Algorithm (Van Buuren, 2012)

- 1: **for**  $j$  in  $1, \dots, 4$ : ▷ Setup
- 2:     Specify imputation model for variable  $X_j$   
       $p(X_j^{mis} \mid X_j^{obs}, X_{-j}, R)$
- 3:     Fill in starting imputations  $\dot{X}_j^0$  by random draws from  $X_j^{obs}$ .
- 4: **end for**
  
- 5: **for**  $t = 1$ : ▷ loop through iterations
- 6:     **for**  $j = 4$ : ▷ loop through variables
- 7:        Define currently complete data except  $X_4$   
           $\dot{X}_{-4}^1 = (\dot{X}_1^1, \dot{X}_2^1, \dot{X}_3^1)$ .
- 8:        Draw parameters  $\dot{\theta}_4^1 \sim p(\theta_4^1 \mid X_4^{obs}, \dot{X}_{-4}^1, R)$ .
- 9:        Draw imputations  $\dot{X}_4^1 \sim p(X_4^{mis} \mid \dot{X}_{-4}^1, R, \dot{\theta}_4^1)$ .
- 10:     **end for**
- 11: **end for**



# The MICE Algorithm (Van Buuren, 2012)

- 1: **for**  $j$  in  $1, \dots, 4$ : ▷ Setup
- 2:     Specify imputation model for variable  $X_j$   
       $p(X_j^{mis} \mid X_j^{obs}, X_{-j}, R)$
- 3:     Fill in starting imputations  $\dot{X}_j^0$  by random draws from  $X_j^{obs}$ .
- 4: **end for**
  
- 5: **for**  $t = 2$ : ▷ loop through iterations
- 6:     **for**  $j = 1$ : ▷ loop through variables
- 7:        Define currently complete data except  $X_1$   
           $\dot{X}_{-1}^2 = (\dot{X}_2^1, \dot{X}_3^1, \dot{X}_4^1)$ .
- 8:        Draw parameters  $\dot{\theta}_1^2 \sim p(\theta_1^2 \mid X_1^{obs}, \dot{X}_{-1}^2, R)$ .
- 9:        Draw imputations  $\dot{X}_1^2 \sim p(X_1^{mis} \mid \dot{X}_{-1}^2, R, \dot{\theta}_1^2)$ .
- 10:     **end for**
- 11: **end for**

# The MICE Algorithm (Van Buuren, 2012)

- 1: **for**  $j$  in  $1, \dots, 4$ : ▷ Setup
- 2:     Specify imputation model for variable  $X_j$   
       $p(X_j^{mis} \mid X_j^{obs}, X_{-j}, R)$
- 3:     Fill in starting imputations  $\dot{X}_j^0$  by random draws from  $X_j^{obs}$ .
- 4: **end for**
  
- 5: **for**  $t = 2$ : ▷ loop through iterations
- 6:     **for**  $j = 2$ : ▷ loop through variables
- 7:        Define currently complete data except  $X_2$   
           $\dot{X}_{-2}^2 = (\dot{X}_1^2, \dot{X}_3^1, \dot{X}_4^1)$ .
- 8:        Draw parameters  $\theta_2^2 \sim p(\theta_2^2 \mid X_2^{obs}, \dot{X}_{-2}^2, R)$ .
- 9:        Draw imputations  $\dot{X}_2^2 \sim p(X_2^{mis} \mid \dot{X}_{-2}^2, R, \theta_2^2)$ .
- 10:     **end for**
- 11: **end for**

# The MICE Algorithm

---

The imputed values from the **last iteration**,

$$\left(\dot{X}_1^T, \dots, \dot{X}_p^T\right),$$

are then used to replace the missing values in the original data.

One run through the algorithm ➔ one imputed dataset.

# The MICE Algorithm

---

The imputed values from the **last iteration**,

$$\left(\dot{X}_1^T, \dots, \dot{X}_p^T\right),$$

are then used to replace the missing values in the original data.

One run through the algorithm ➔ one imputed dataset.

➔ To obtain  $m$  imputed datasets: **repeat  $m$  times**

# Iterations & Convergence

---

- ▶ The **sequence of imputations** for one missing value (from starting value to final iteration) is called a **chain**.
- ▶ Each run through the MICE algorithm produces one chain per missing value.

## Why iterations?

# Iterations & Convergence

---

- ▶ The **sequence of imputations** for one missing value (from starting value to final iteration) is called a **chain**.
- ▶ Each run through the MICE algorithm produces one chain per missing value.

## Why iterations?

- ▶ **Imputed values** in one variable **depend on** the imputed values of the **other variables** (Gibbs sampling).
- ▶ If the starting values (random draws) are far from the actual distribution, imputed values from the first few iterations are not draws from the distribution of interest.

# Iterations & Convergence

---

## How many iterations?

Until **convergence**

= when the sampling distribution does not change any more

(Note: the imputed value will still vary between iterations.)

# Iterations & Convergence

---

## How many iterations?

Until **convergence**

= when the sampling distribution does not change any more

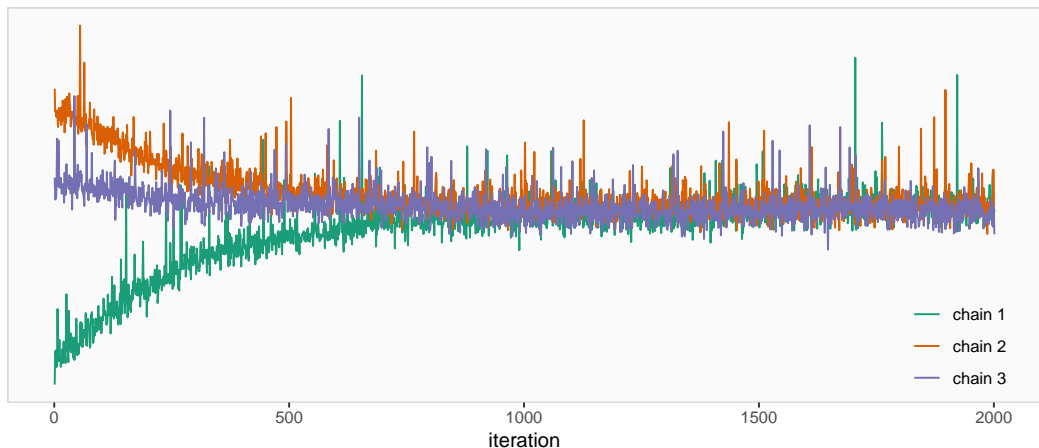
(Note: the imputed value will still vary between iterations.)

## How to evaluate convergence?

The **traceplot** (x-axis: iteration number, y-axis: imputed value) should show a horizontal band

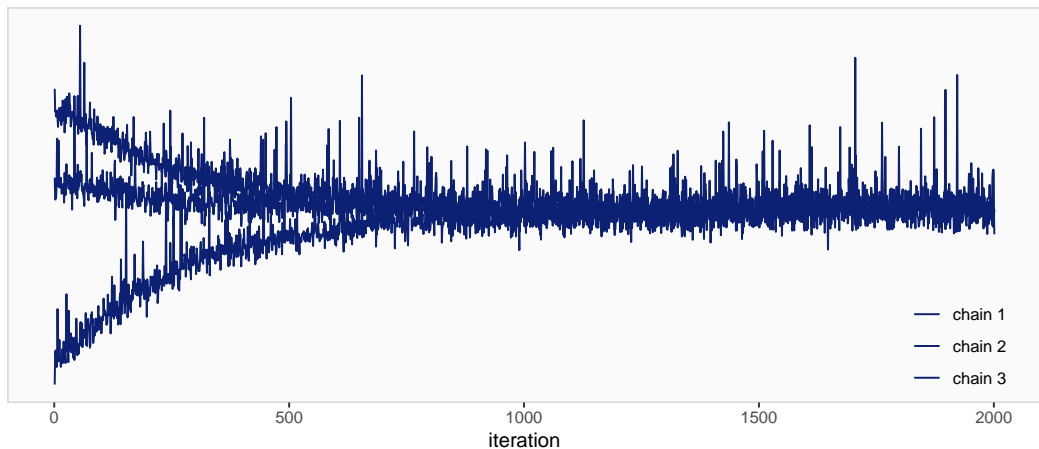


# Checking Convergence



Each chain is the sequence of imputed values (from starting value to final imputed value) for the same missing value.

# Checking Convergence



Each chain is the sequence of imputed values (from starting value to final imputed value) for the same missing value.

# Checking Convergence

---

In imputation we have

- ▶ several **variables** with missing values (e.g.,  $p$ )
  - ▶ several missing **values** in each of these variables
  - ▶  $m$  **chains** for each missing value
- ➔ possibly a large number of MCMC chains

To check all chains separately could be very time consuming in large datasets.

# Checking Convergence

---

In imputation we have

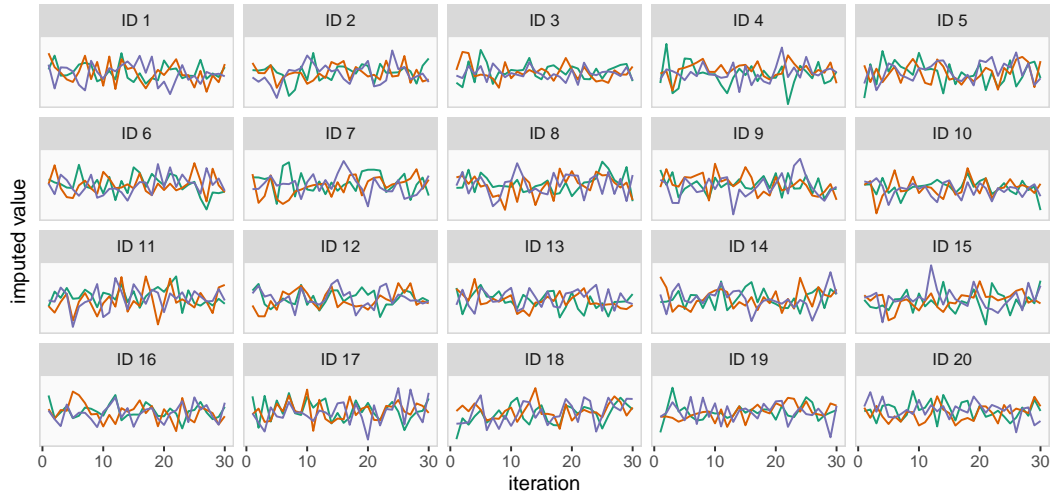
- ▶ several **variables** with missing values (e.g.,  $p$ )
  - ▶ several missing **values** in each of these variables
  - ▶  $m$  **chains** for each missing value
- ➔ possibly a large number of MCMC chains

To check all chains separately could be very time consuming in large datasets.

**Alternative:** Calculate and plot a summary (e.g., the mean) of the imputed values over all subjects, separately per chain and variable

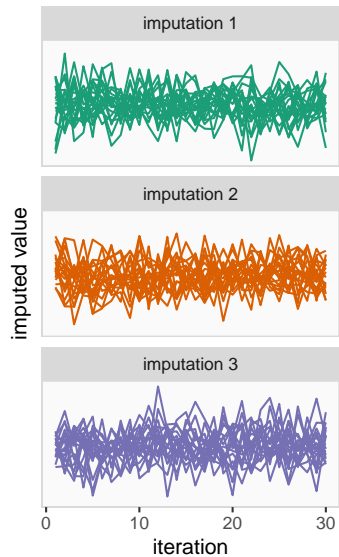
➔ only  $m \times p$  chains to check

# Checking Convergence

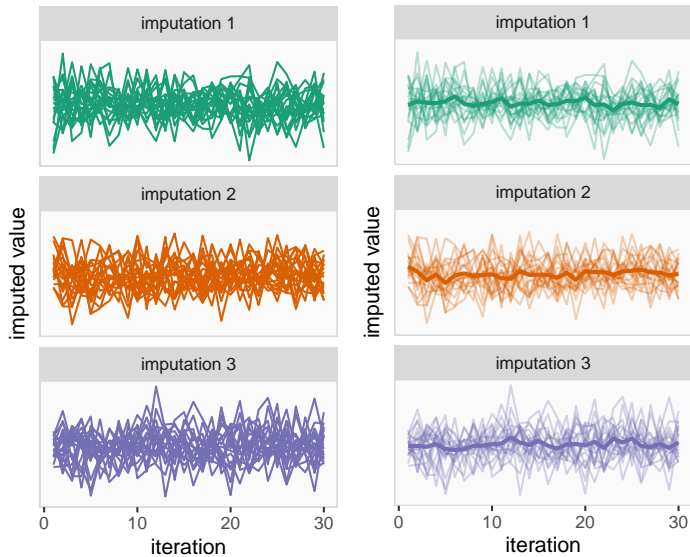


imputation number: — 1 — 2 — 3

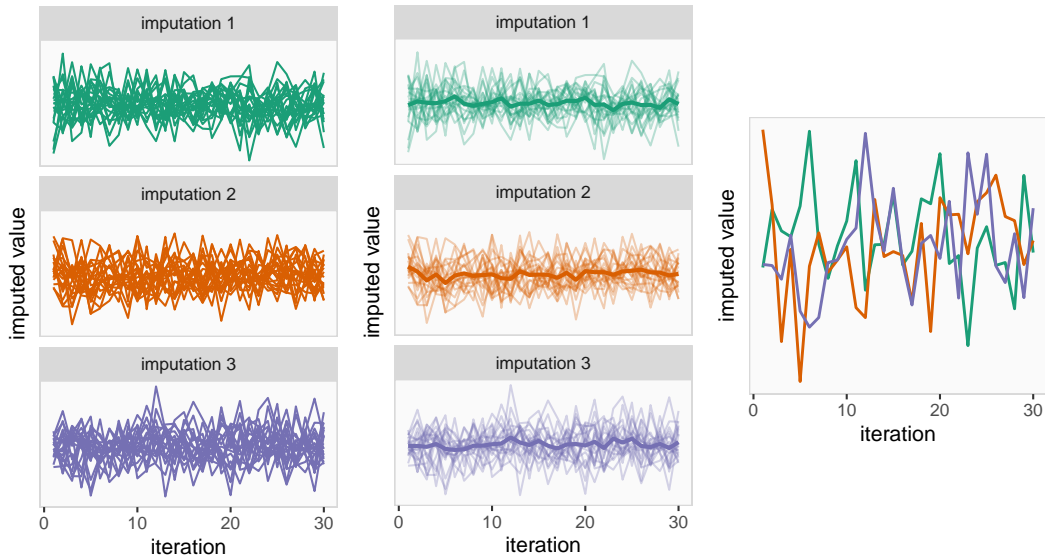
# Checking Convergence



# Checking Convergence



# Checking Convergence





## References

---

Van Buuren, S. (2012). *Flexible Imputation of Missing Data*. Taylor & Francis. <https://stefvanbuuren.name/fimd/>